

Defect detection in ReBCO layers using Machine Learning

Nandana Menon¹, Jean-Francois Croteau¹, Ian Pong¹, Yavuz Oz², Hannah Pimentel², Dmytro
Abraimov²

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¹Lawrence Berkely National Lab, ²Applied Superconductivity Center, National High Magnetic Field Laboratory, Florida State University

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– CNN, reusing models, annotation, data pre-processing

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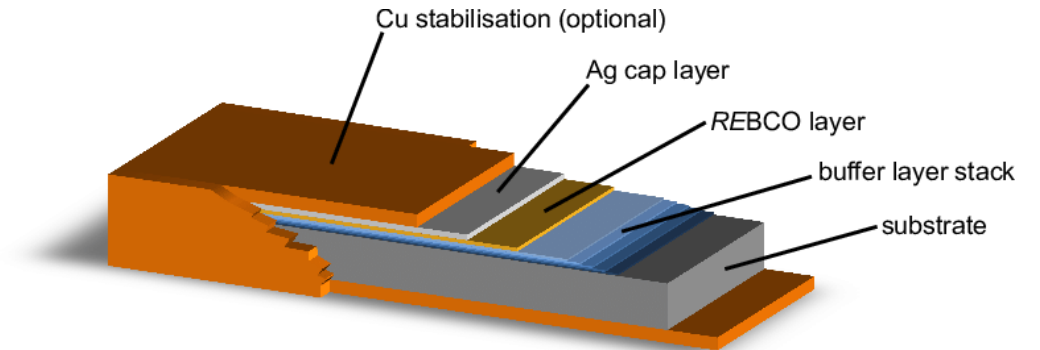
Comparison of the two models

06

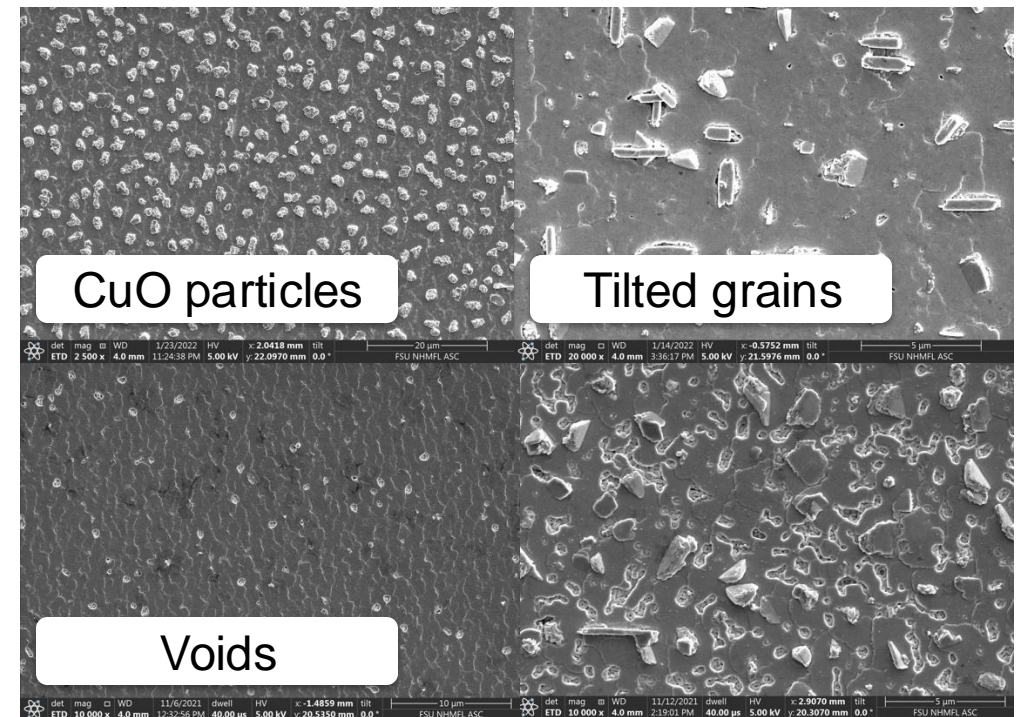
Conclusion

Larger goal

- Correlating transport and mechanical properties to microstructure
- Characterization of ReBCO conductors of varying thickness between $0.6 - 1.9 \mu\text{m}$
- SEM of top layer after etching out Cu and Ag layers to reveal ReBCO layer
- Defects: voids, CuO particles, and a-axis grains



C Barth et al 2015 *Supercond. Sci. Technol.*

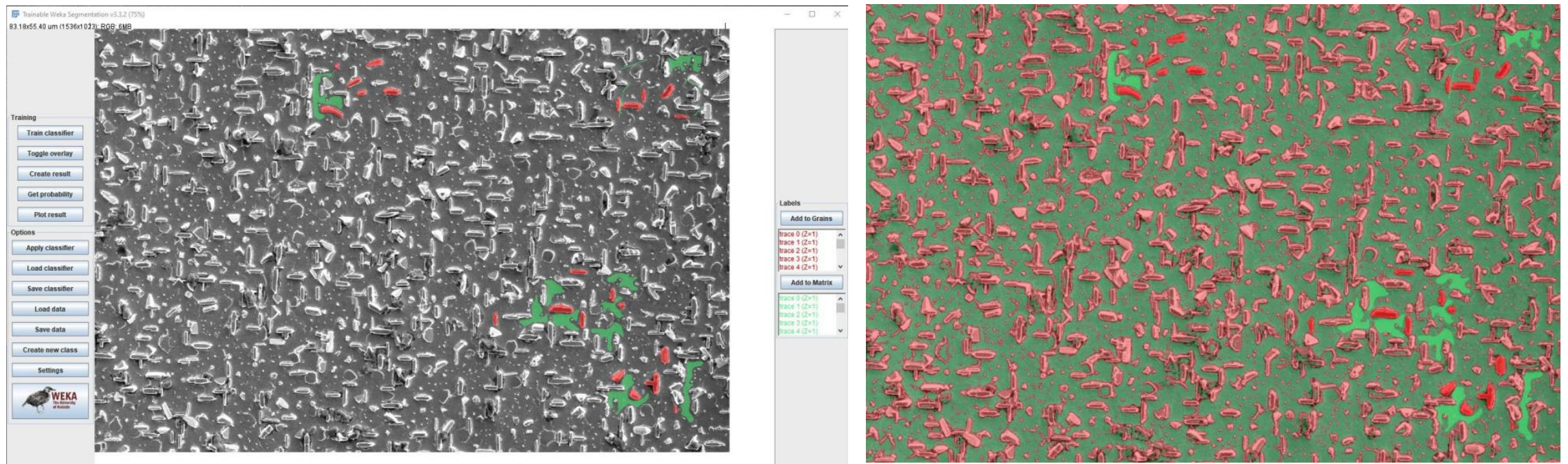


Imaging and etching done at FSU by D. Abraimov et al.

Defect detection

Existing methodologies

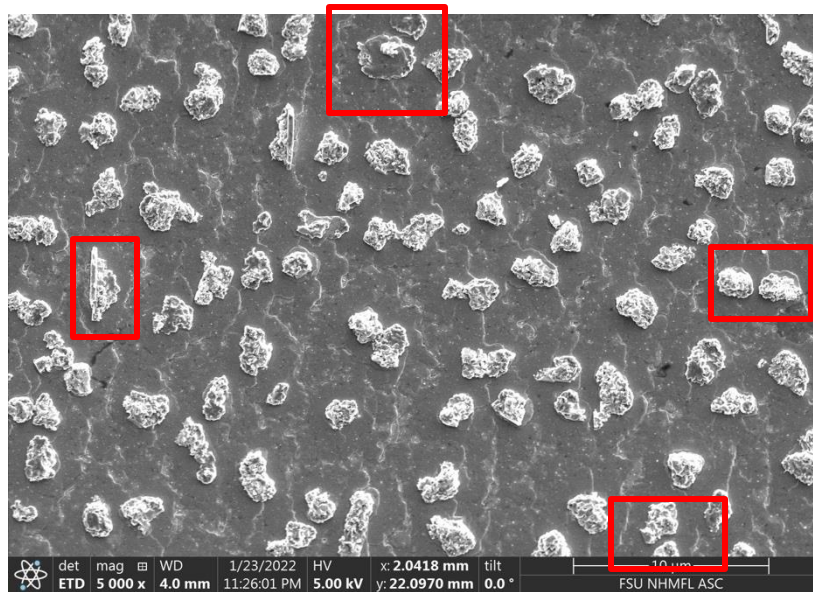
- Counting defects manually
- Built-in ML techniques within image analysis software (ImageJ)



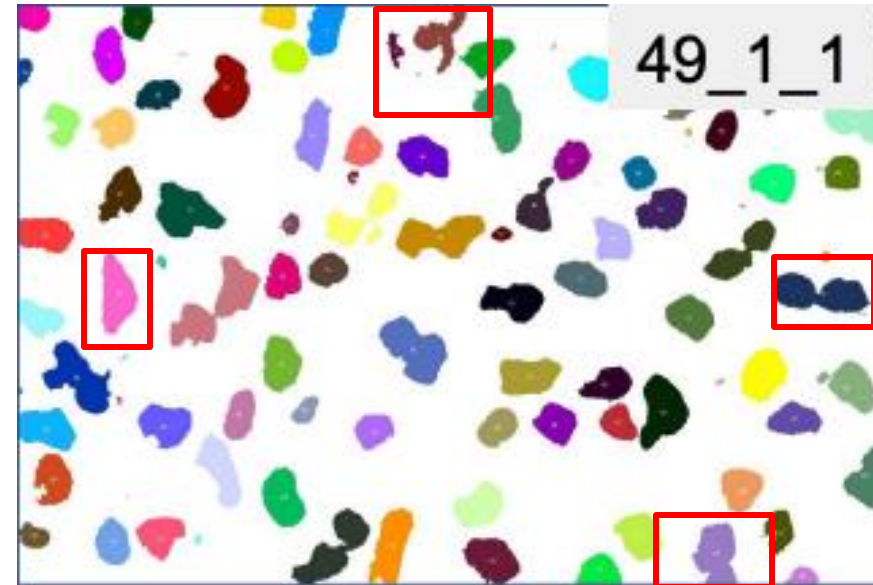
Fiji Trainable Weka Segmentation

Defect detection

Fiji Trainable Weka Segmentation



Origins of low-temperature in-field J_c variability in modern MOCVD ReBCO tapes



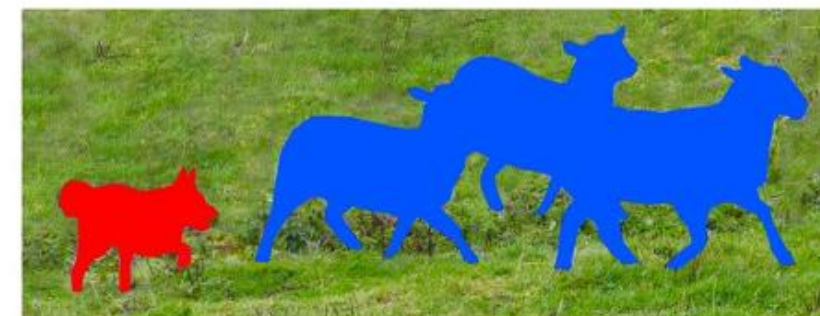
- Annotations need to be drawn
- Elementary ML models
- Features are not learned but user-defined
- Integration for analysis can be difficult
- Data wrangling

Convolution Neural Networks

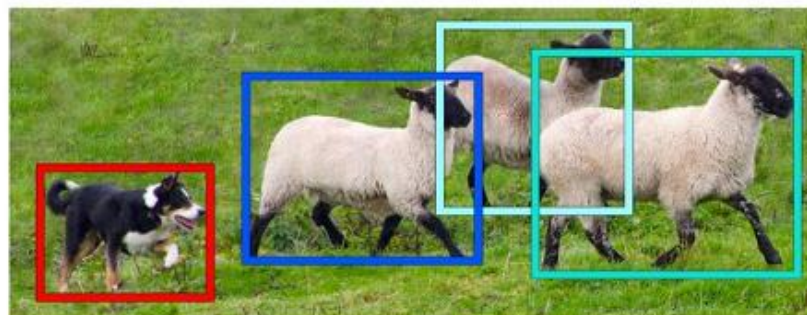
- Image recognition (classification)
- Object detection
- Segmentation



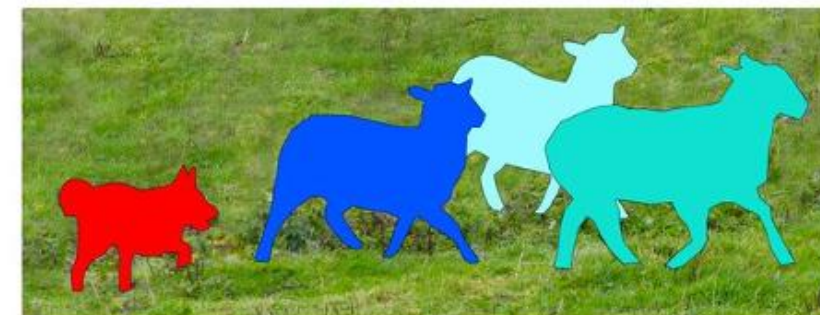
Image Recognition



Semantic Segmentation



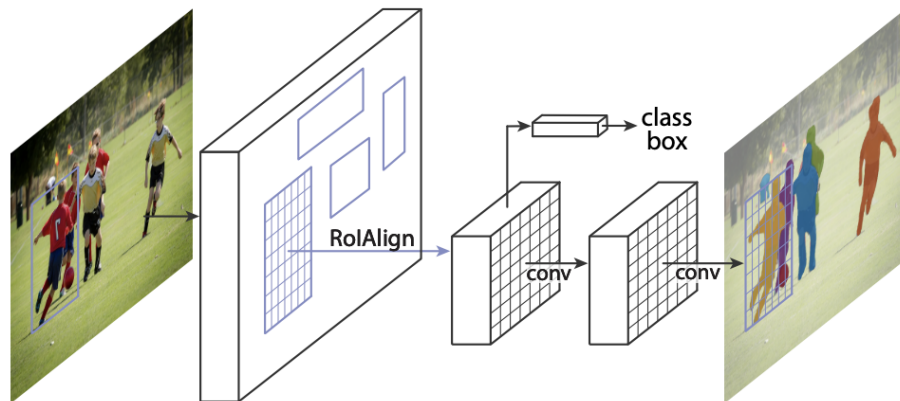
Object Detection



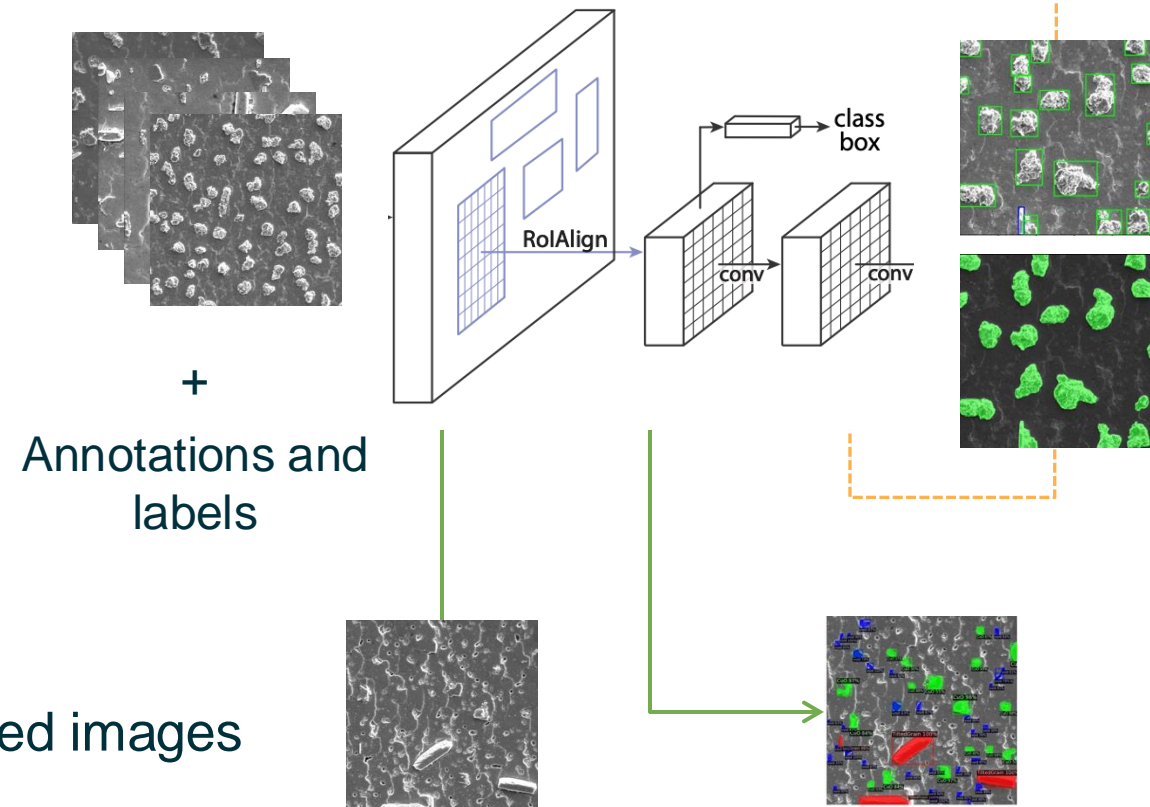
Instance Segmentation

Reusing foundational models

1 Select pre-trained model (~118K images)



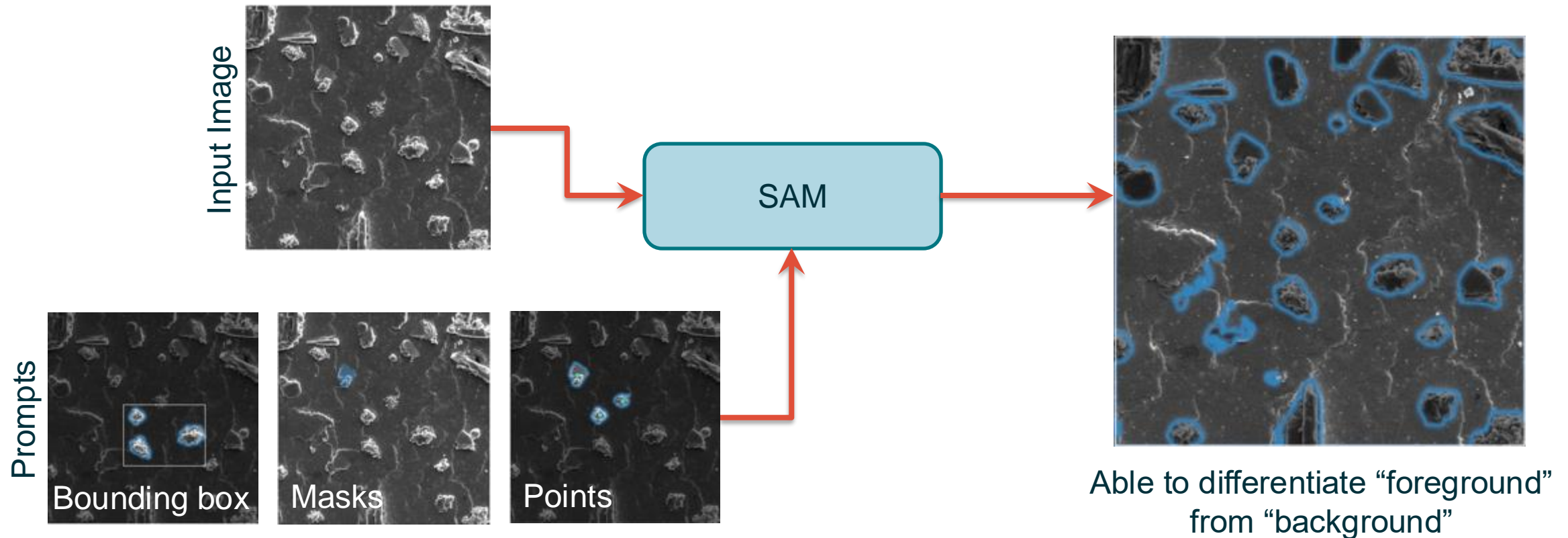
2 Training and Evaluation



3 Final goal – test on unlabeled images

Segment Anything Model (SAM)

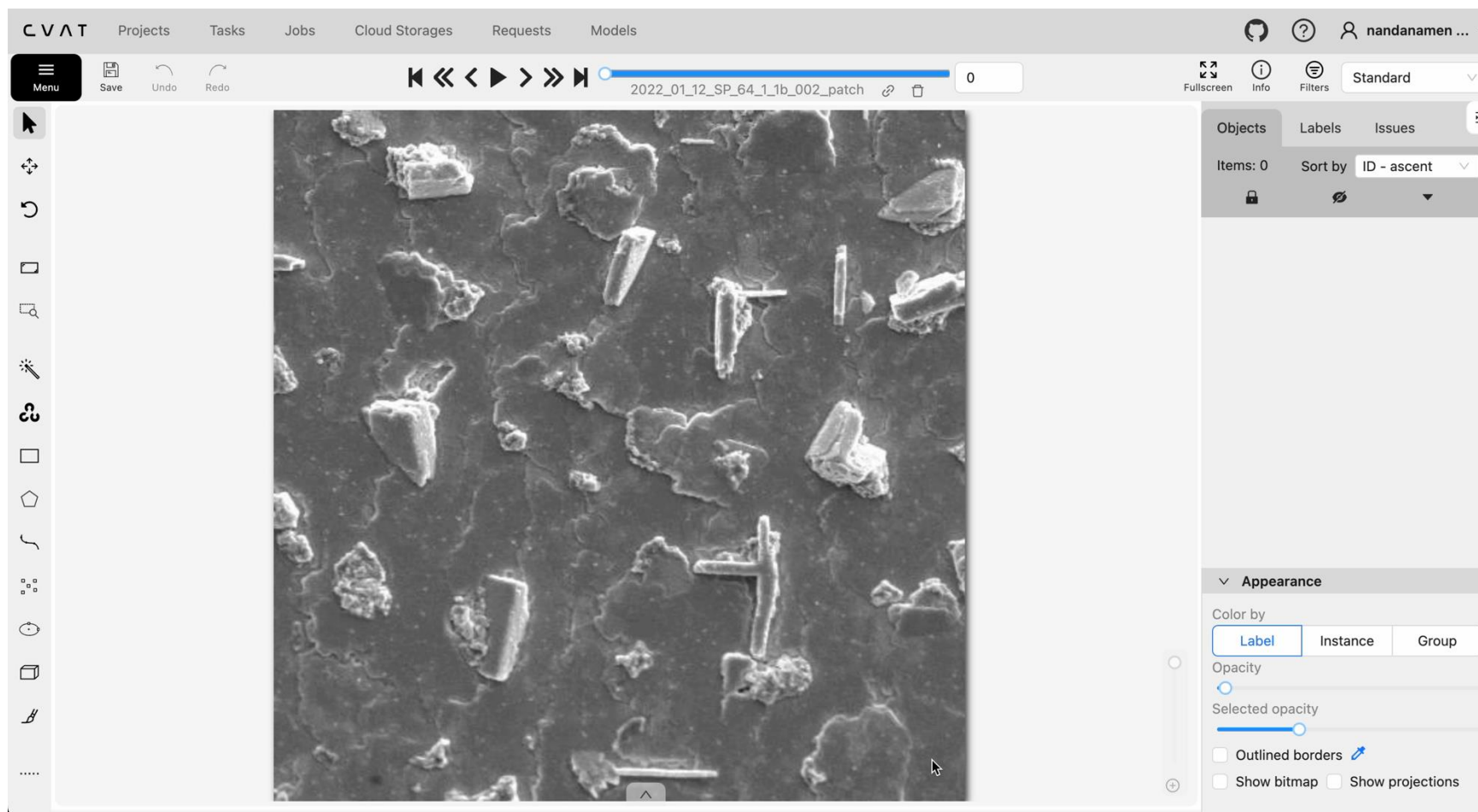
Prompts specifying what to segment in an image allows segmentation without the need for additional training



Backend SAM for annotation

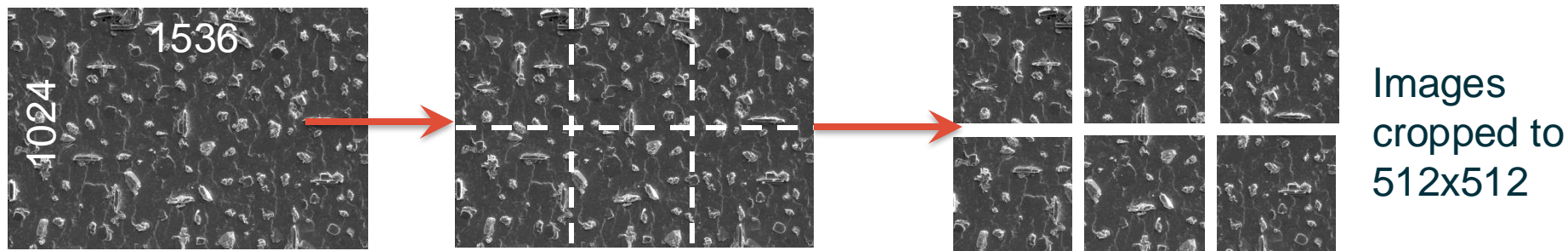
Zero-shot learning allows for interactive segmentation

cvat.ai

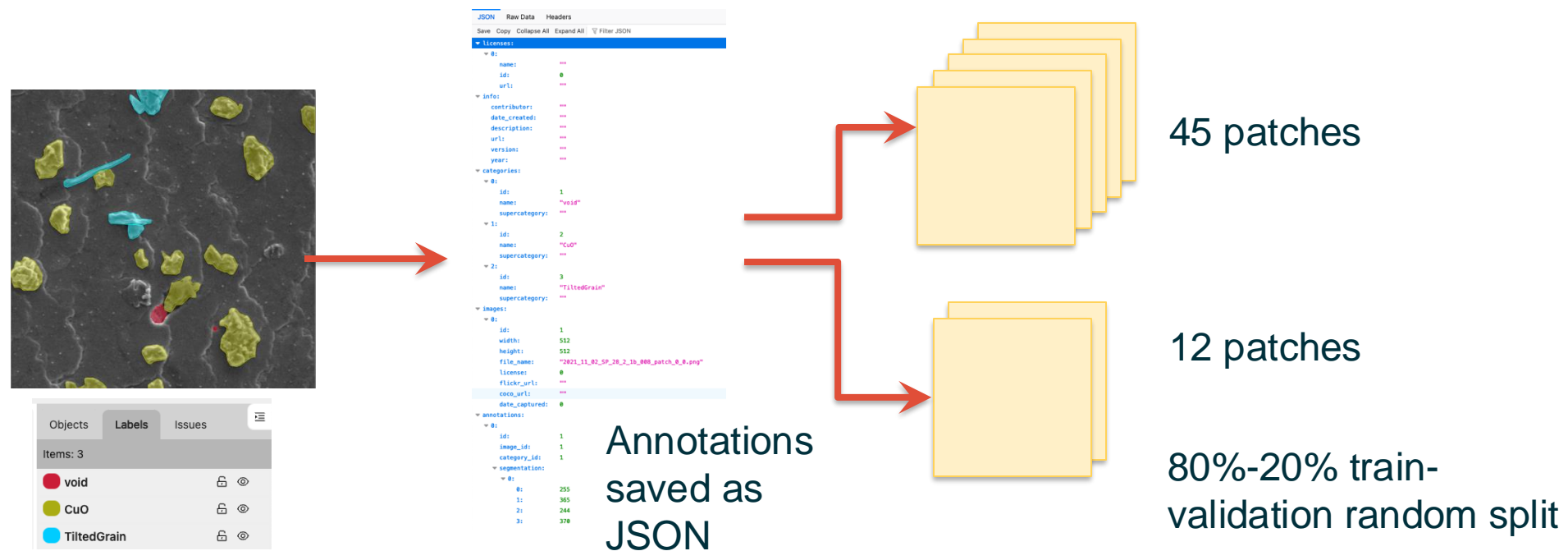


Data preparation

1 Patch images



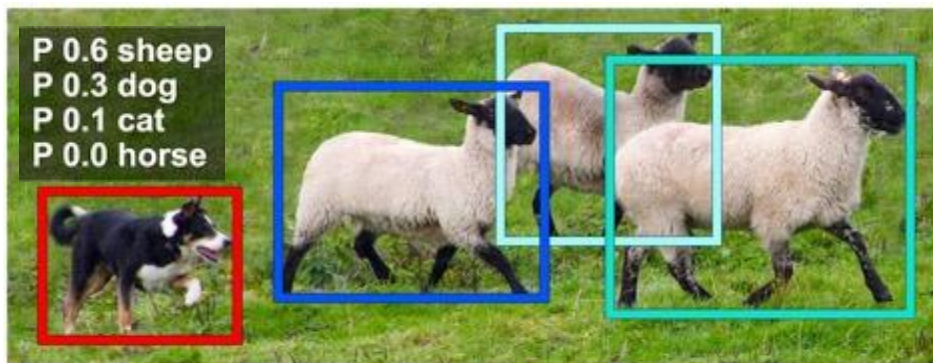
2 Annotating



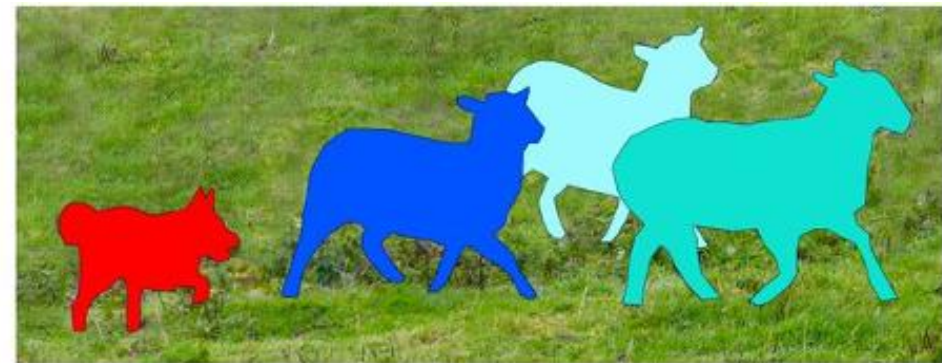
Detectron2: Mask R-CNN



- Rapid implementation of Mask Region-based Convolutional Neural Network (R-CNN)
- 2 step-models
 - 1. Region proposals to determine regions with objects
 - 2. Bounding box refinement and classification, Instance segmentation using a CNN in region proposal
- Outputs: Masks, Bounding boxes, Classes, Scores



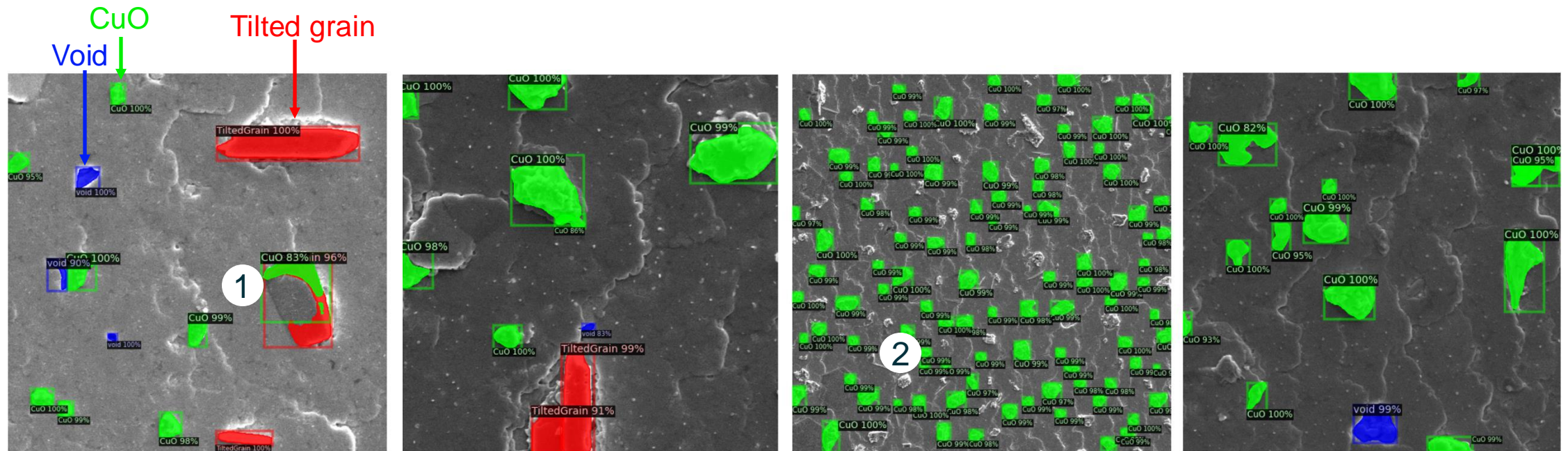
Object detection + Classification



Instance Segmentation

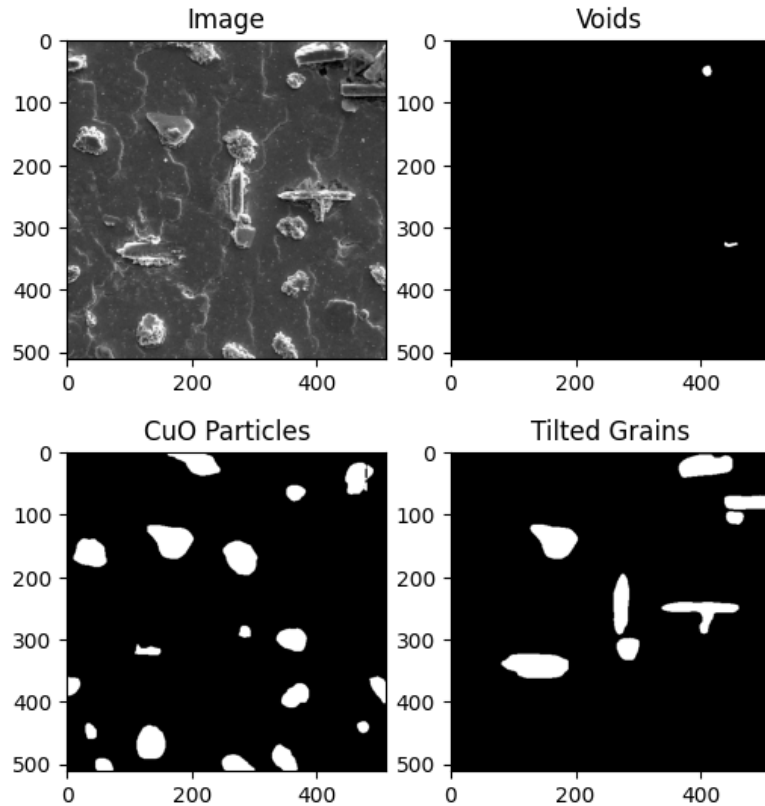
Validation results: Visualized

- ~ 15 mins to train for 5000 iterations on 1 GPU, 12.3 secs inference on CPU
- Some cases of partial masks (1) and missing instances (2)



Validation results: Visualized

Statistics from single image



Void = 2

CuO particles = 18

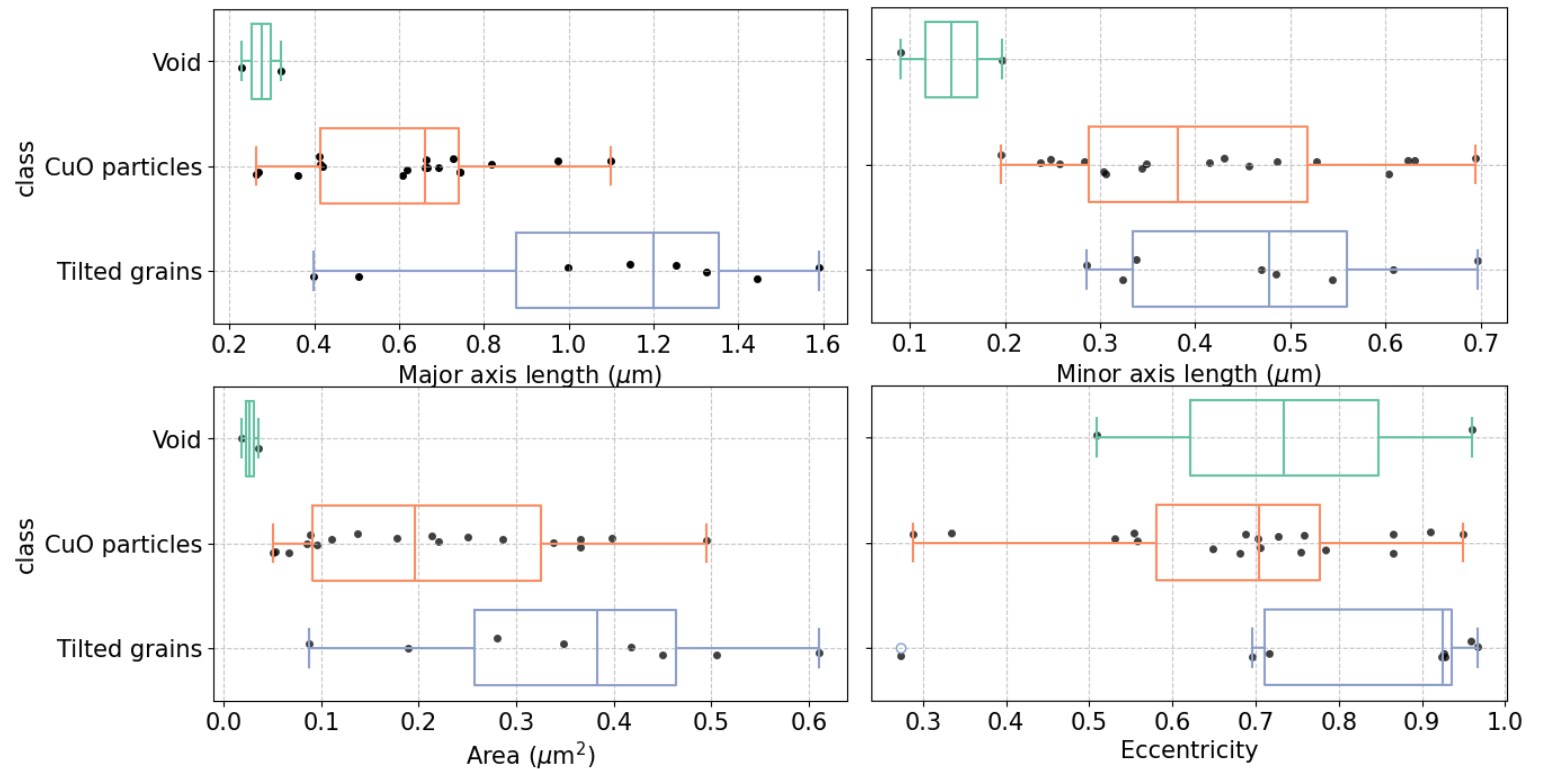
Tilted grains = 8

Fitted ellipse:



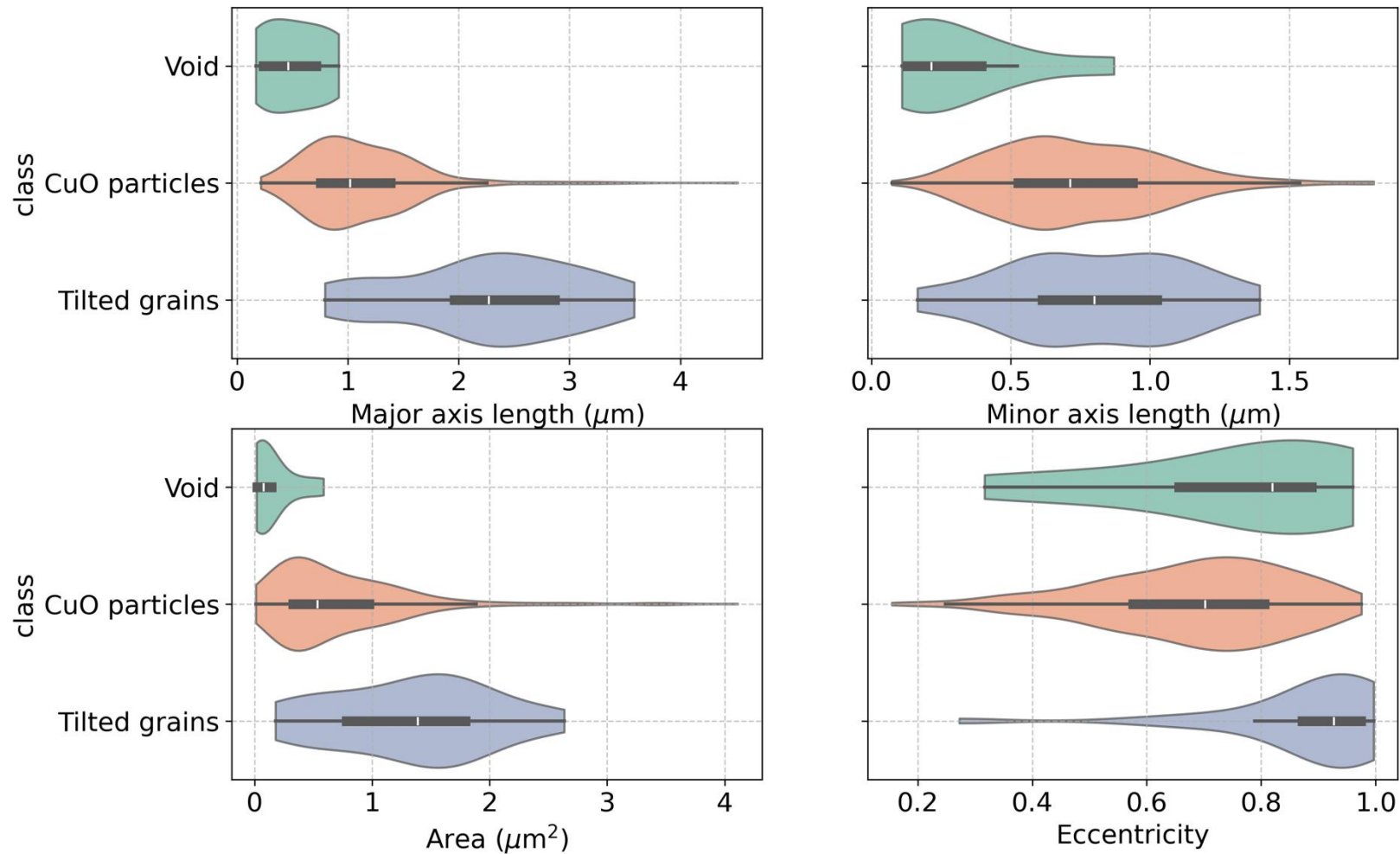
Minor axis

Major axis



Validation results: Visualized

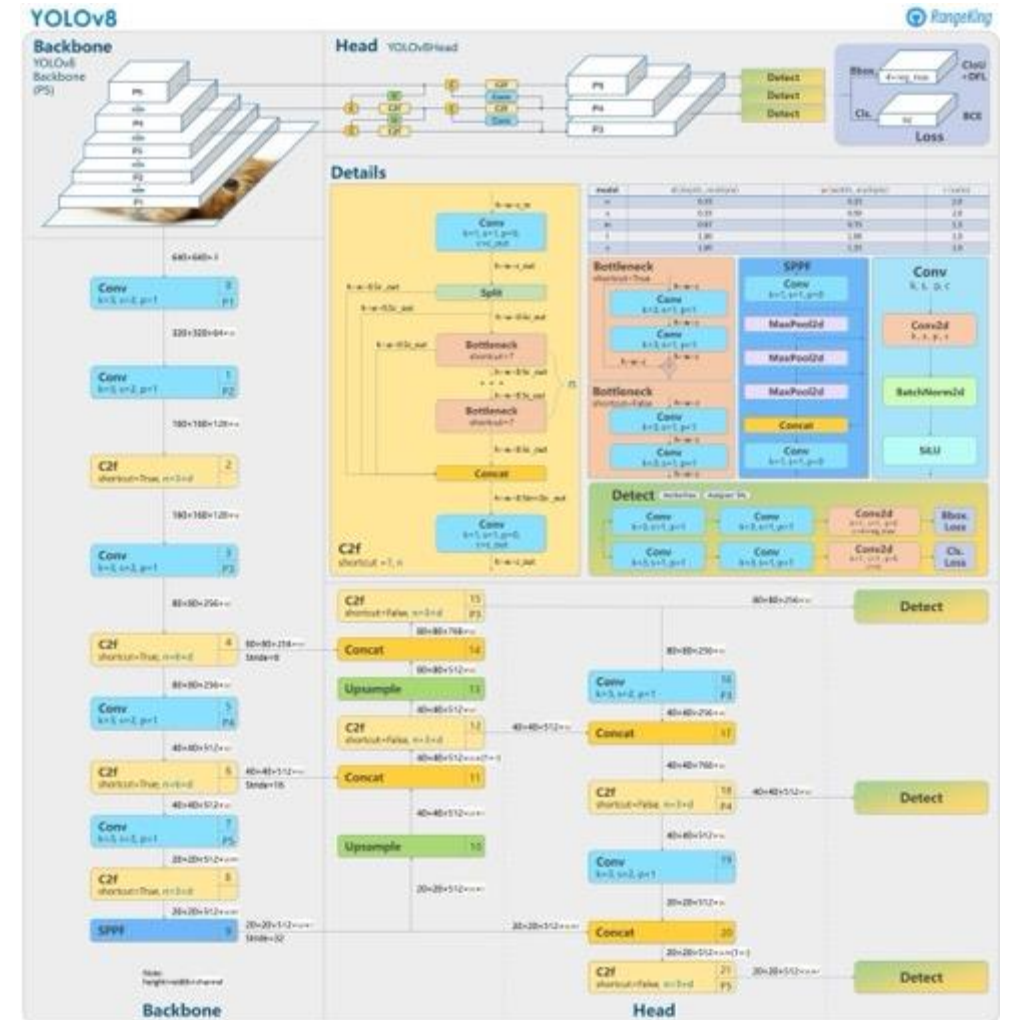
Statistics from all images



YOLOv8

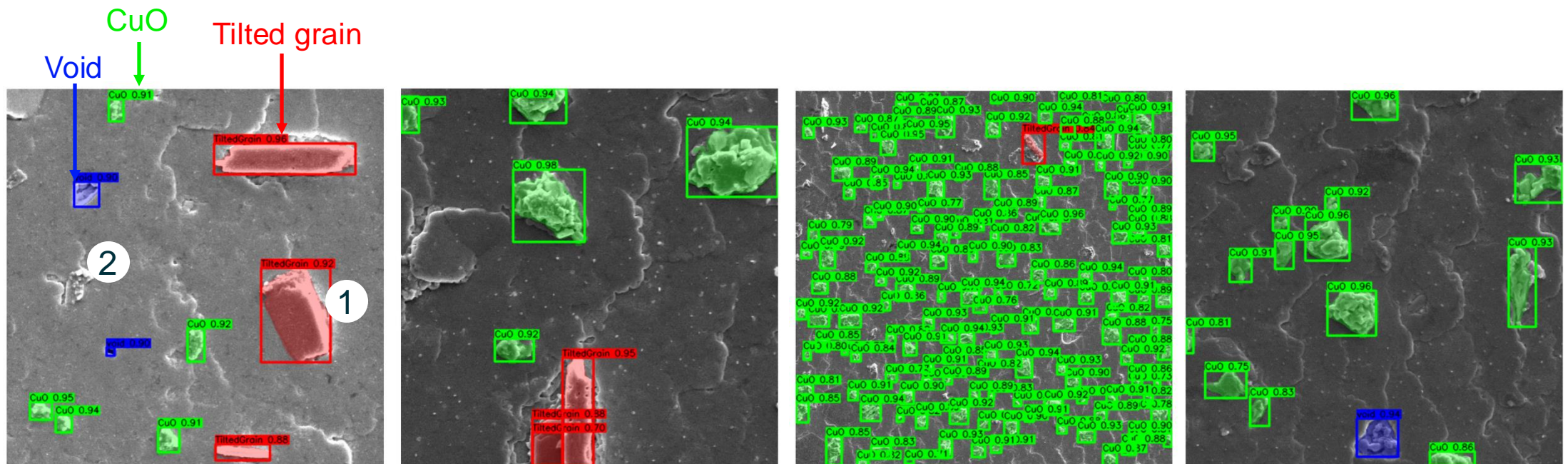


- You Only Look Once: Single-step detection and segmentation
- Relatively larger model size
- Faster inference → better for real-time detection



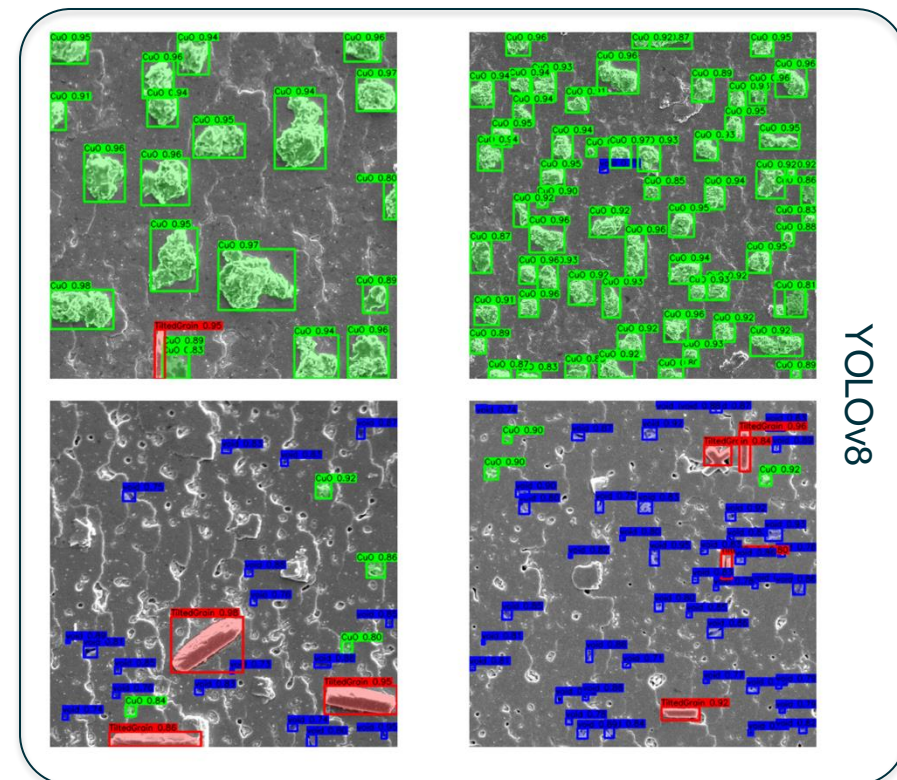
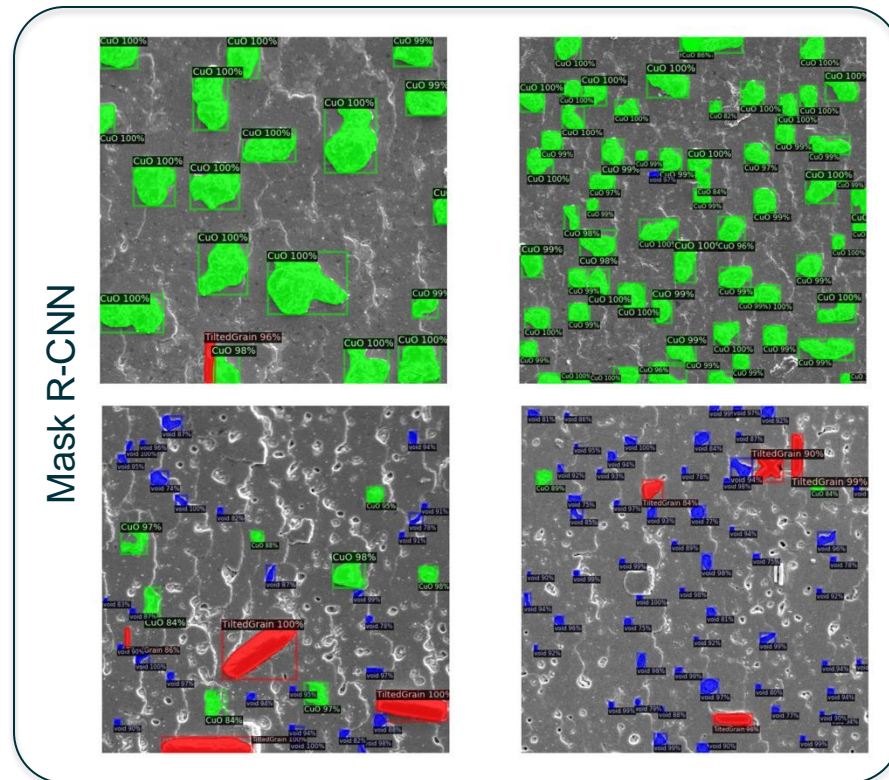
Validation results: Visualized

- ~ 3 hrs. to train for 5000 iterations on 1 GPU, 3.2 secs inference on CPU
- No partial masks like Mask R-CNN (1)
- Some cases of obvious instances not being detected (2)



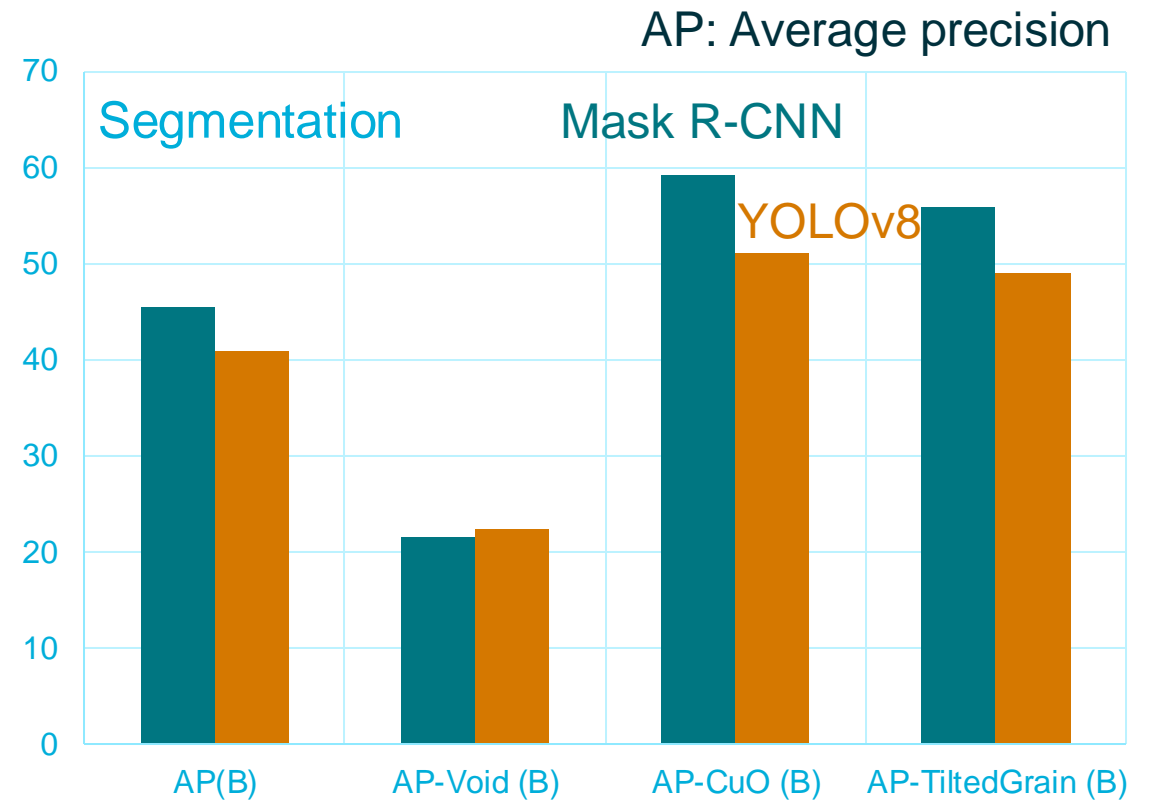
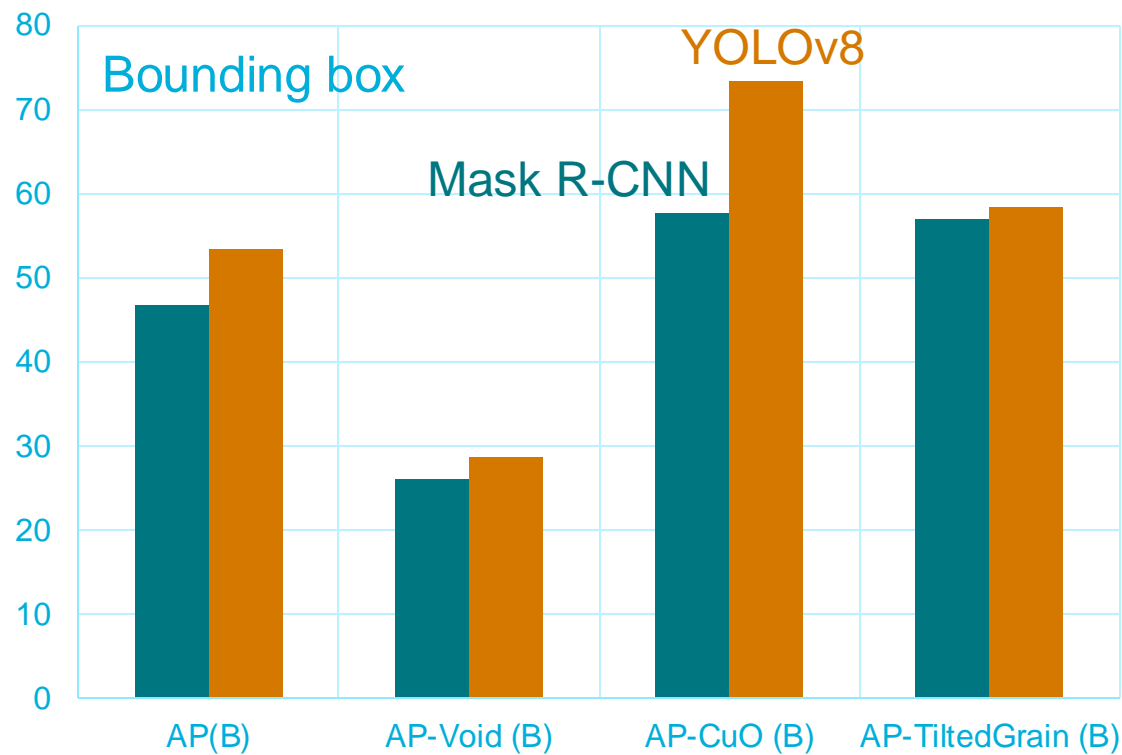
Performance on test images

- Near perfect predictions on 'clear' images
- Issues with messy images (none used for train/validation) but still identifies the less ambiguous defects, especially voids



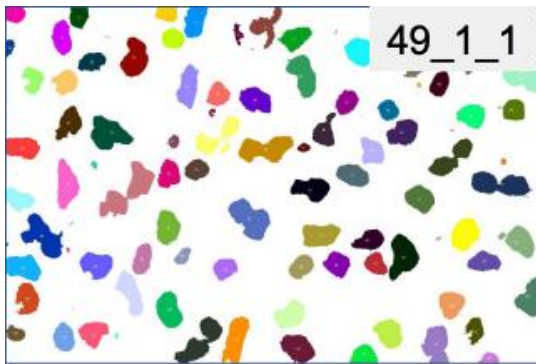
Comparison

Bounding box detection is better by YOLO while segmentation is better by Mask R-CNN

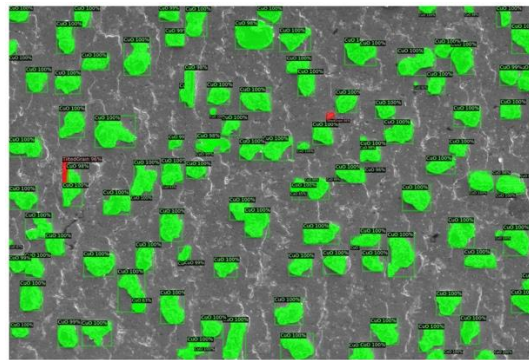


Concluding remarks

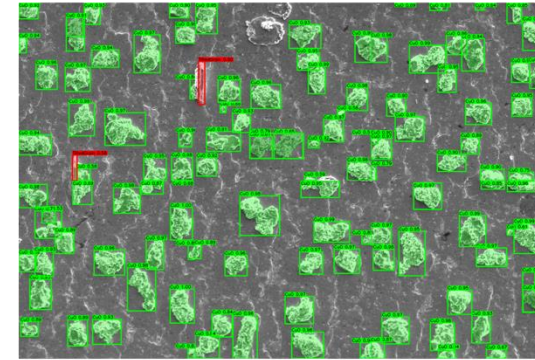
- Main takeaways:
 - SAM for annotation
 - Detectron2/ YOLO for object detection and instance segmentation
 - End-to-end solution for automating analyses
 - Models evolving by the day
- Next steps:
 - Models are only as good as labeled training data – train more to predict better
 - Correlate properties with the defects to find the origins of variation



Fiji Weka (ImageJ)



Mask R-CNN



YOLOv8

Thank You