

LIPEI DU

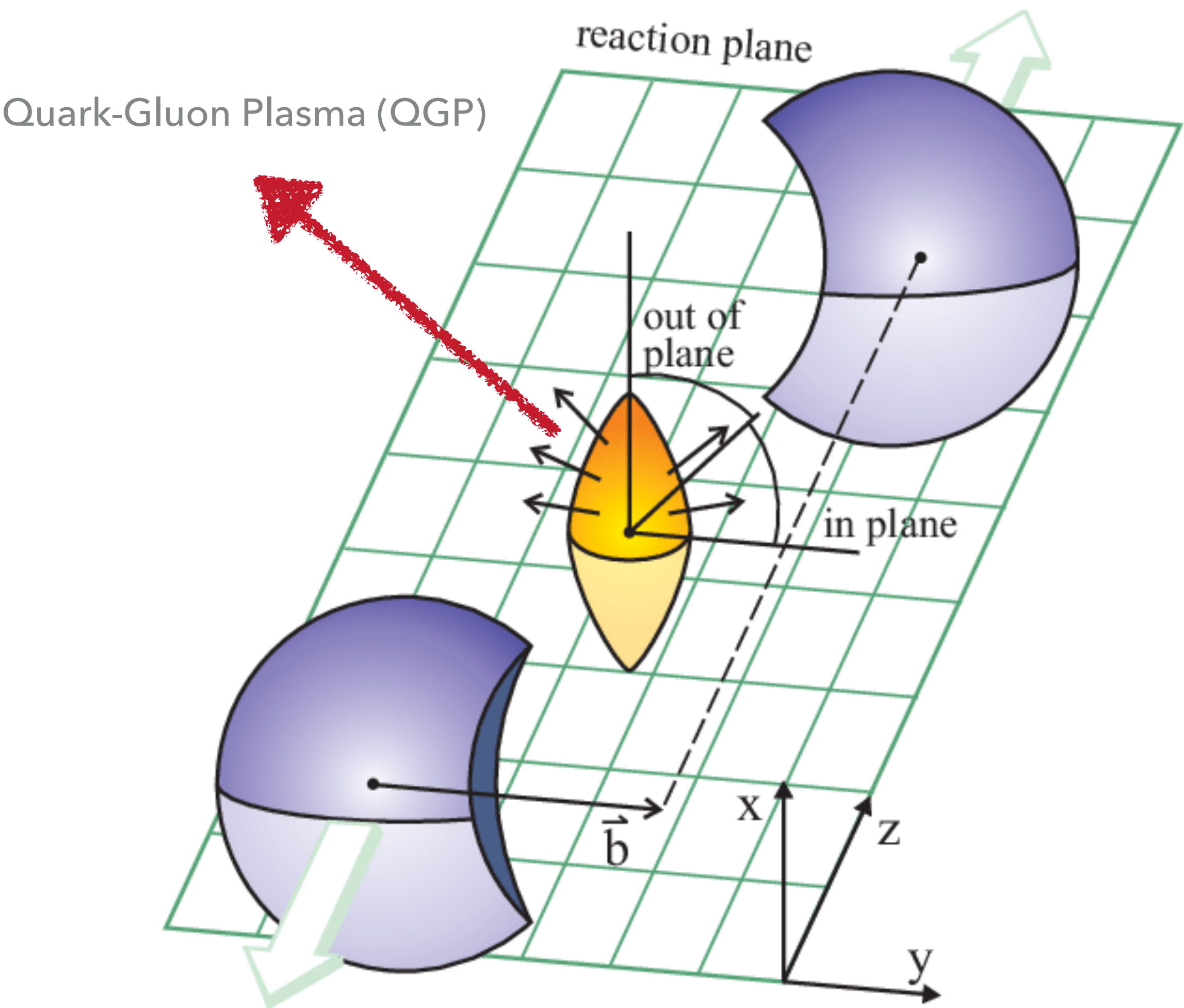
UC BERKELEY & LBNL

BAYESIAN EXPLORATION OF SOFT-HARD INTERPLAY IN HEAVY-ION COLLISIONS

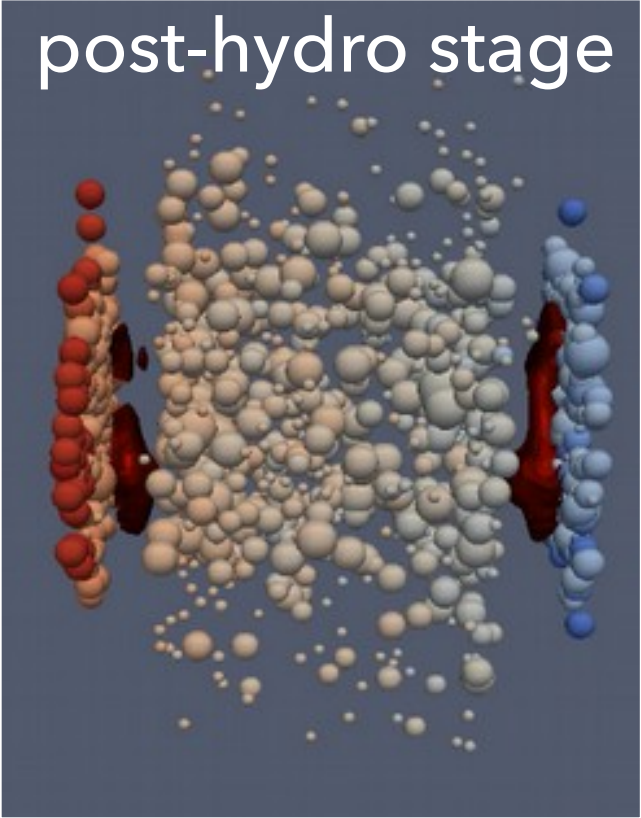
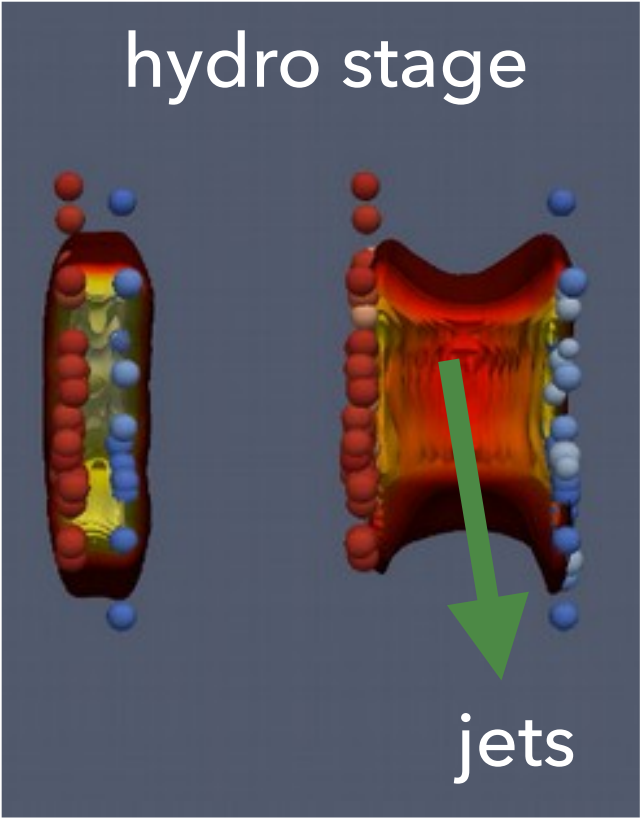
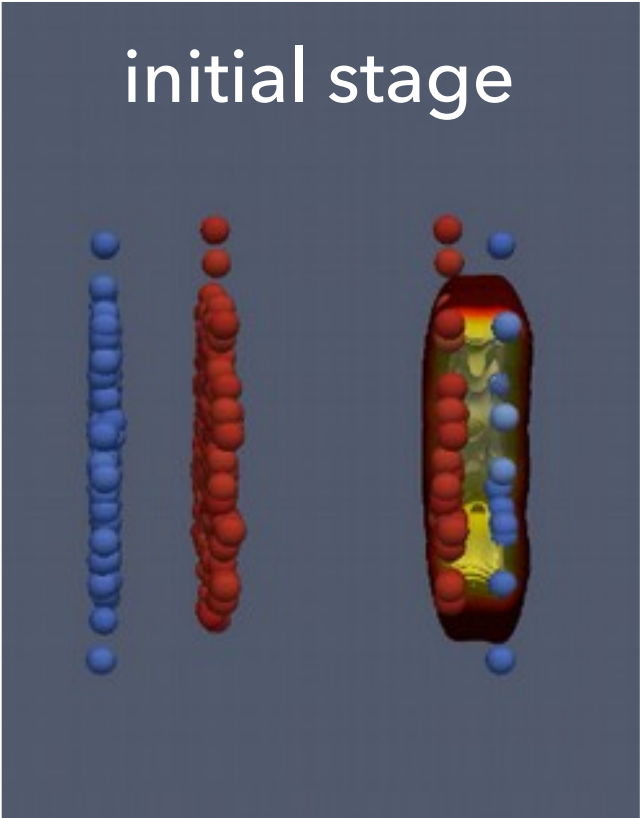
BUQ MEETING

OCTOBER 22, 2025

HEAVY-ION COLLISIONS



time

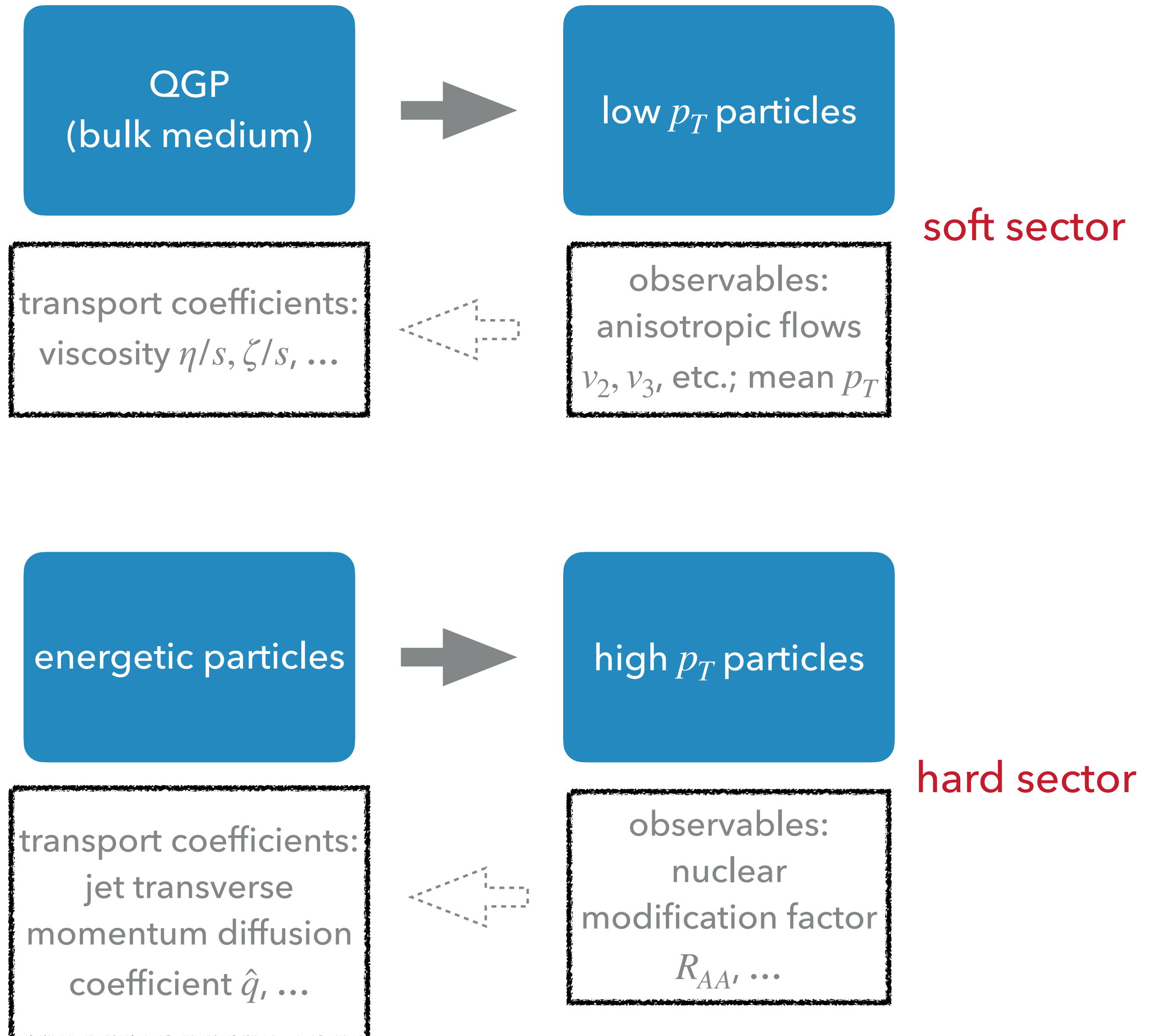
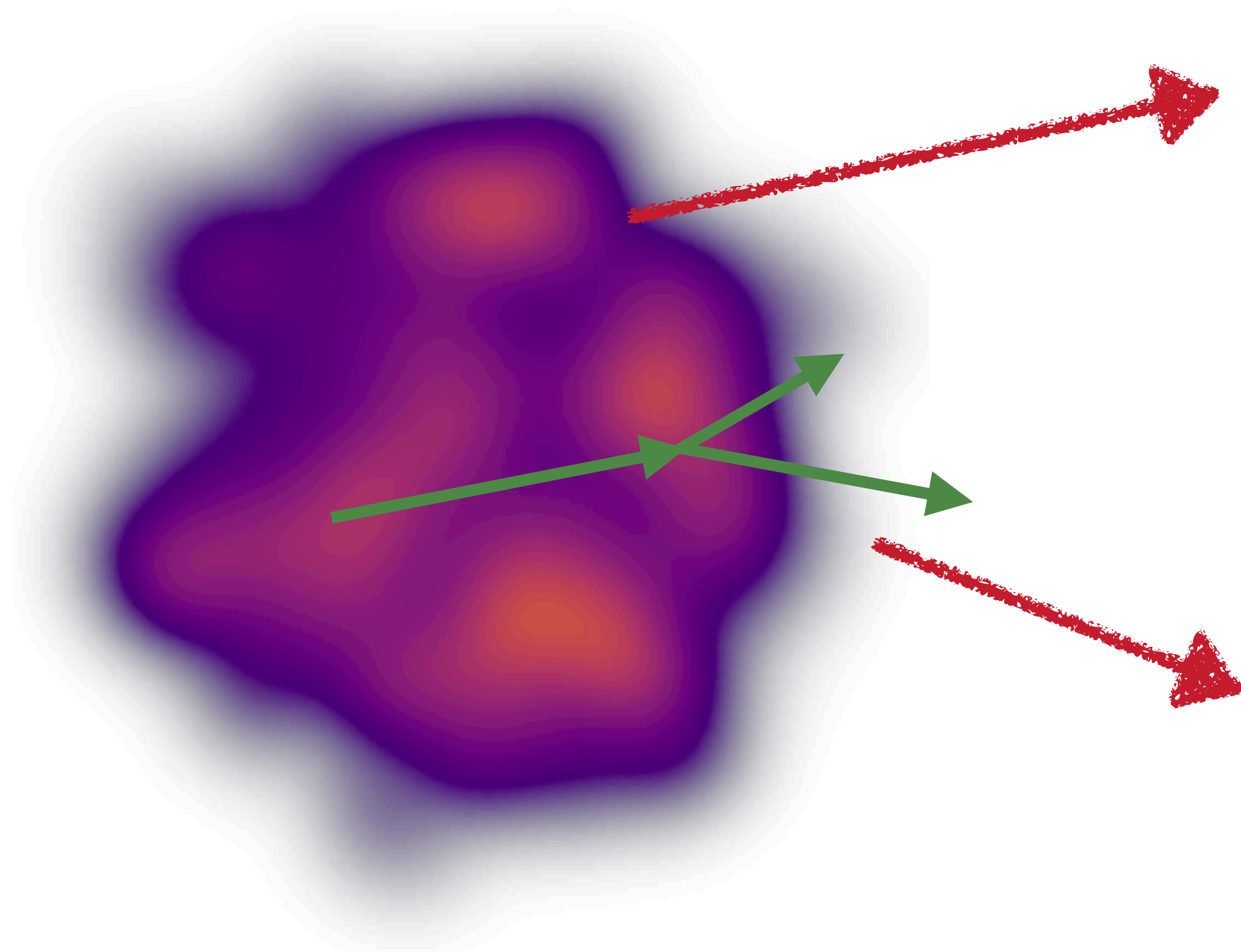


initial conditions
(Trento+free-streaming)

viscous hydrodynamics
(MUSIC)

particle sampler
(iSS)

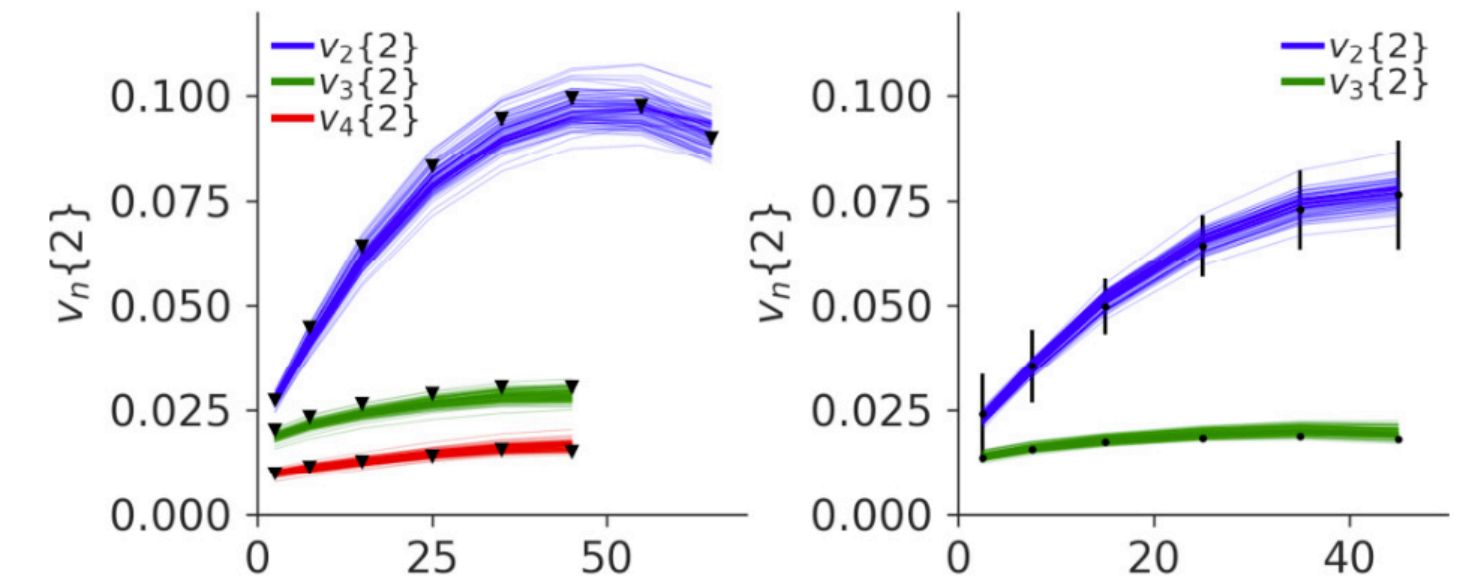
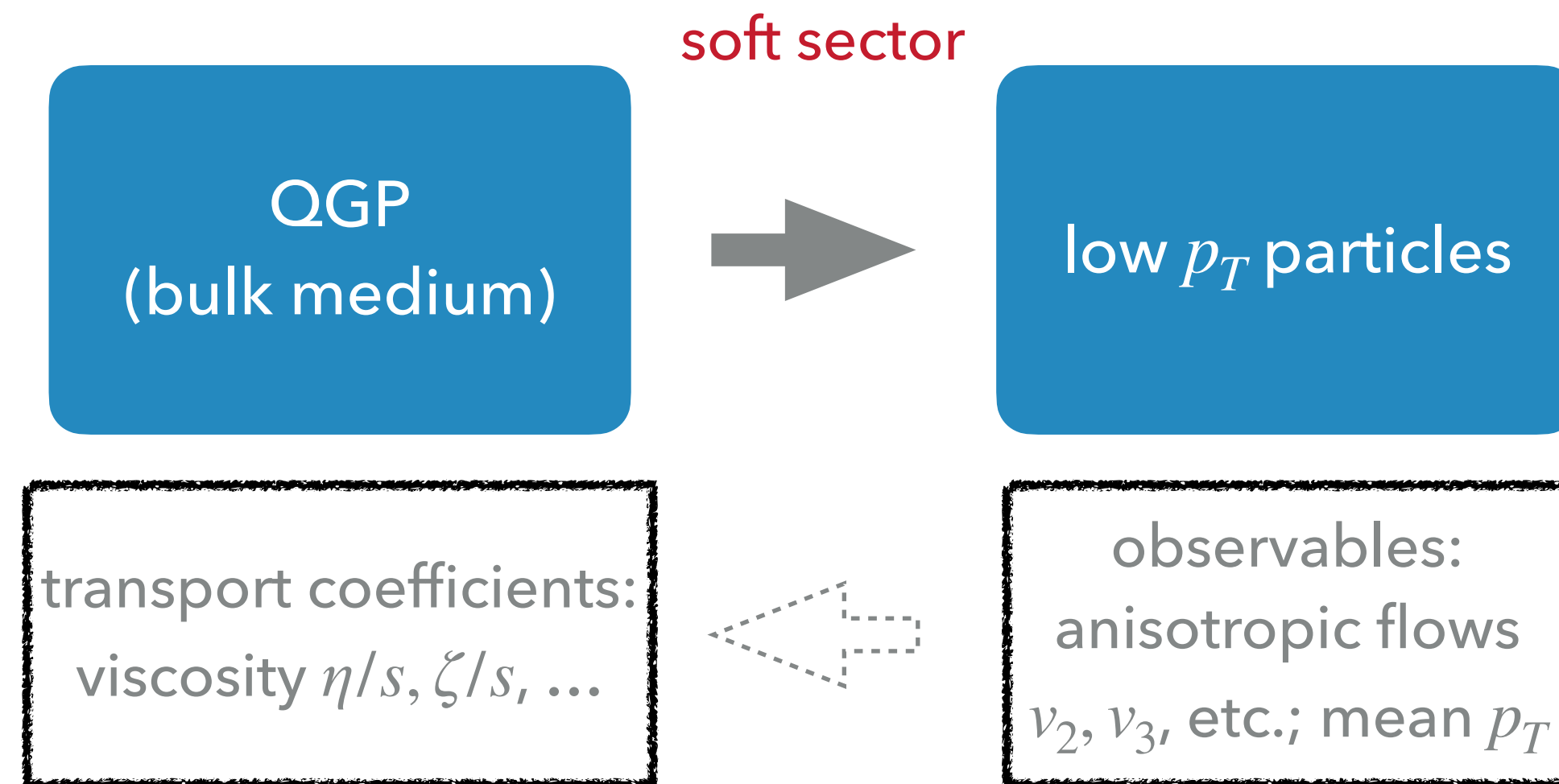
hadronic transport
(SMASH)



$$P(\theta_s, \theta_h \mid D_s, D_h) \propto P(D_s, D_h \mid \theta_s, \theta_h) \cdot P(\theta_s, \theta_h)$$

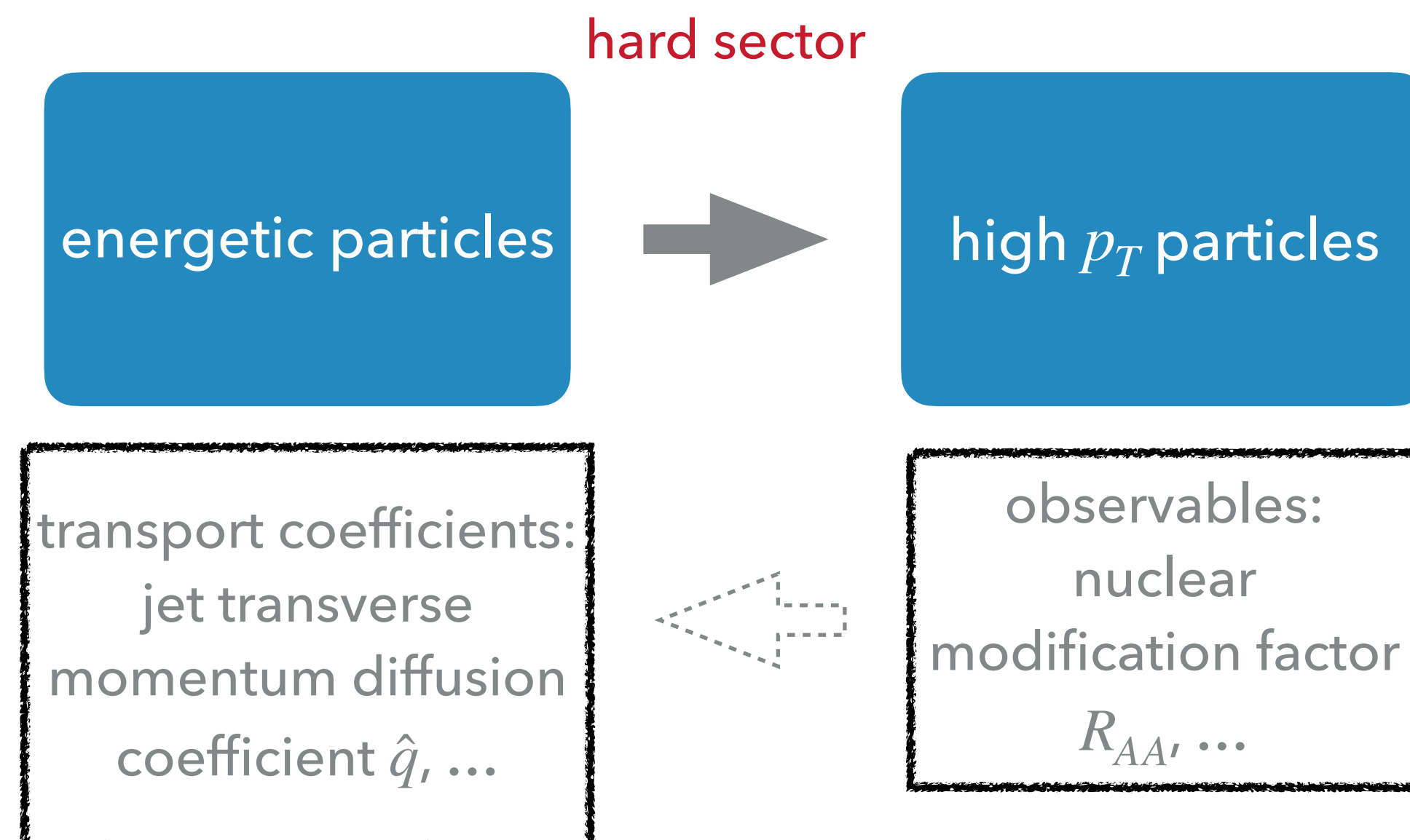
SEPARATE INFERENCE

4

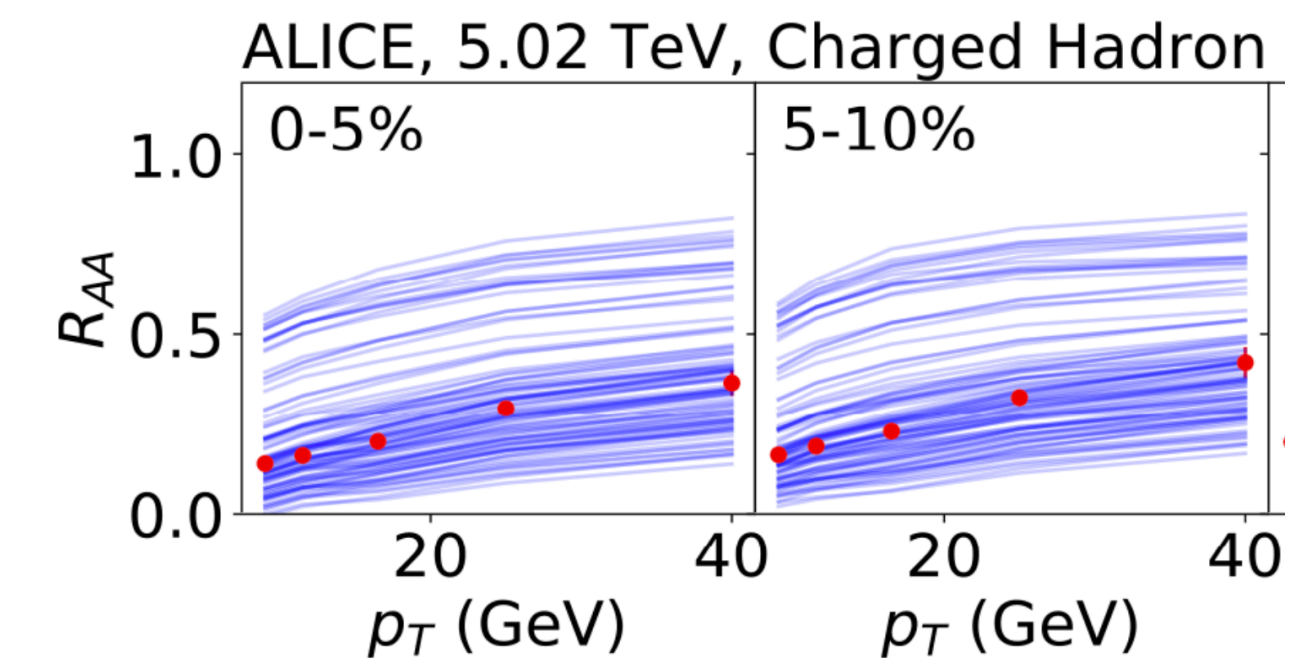


$$P(\theta_s | D_s) \propto P(D_s | \theta_s) \cdot P(\theta_s)$$

► missing constraints from D_h

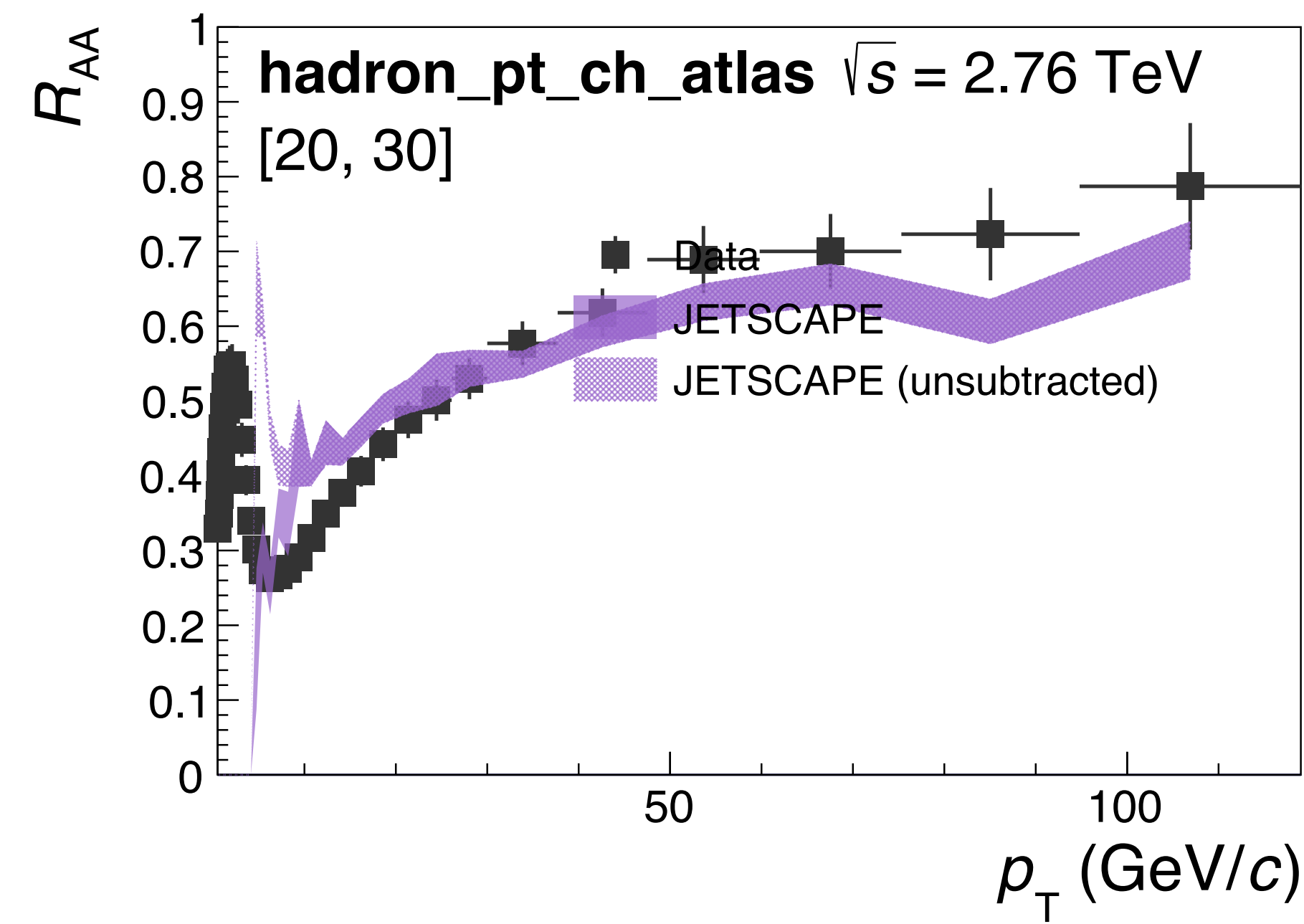


bulk medium
evolution with
fixed θ_s

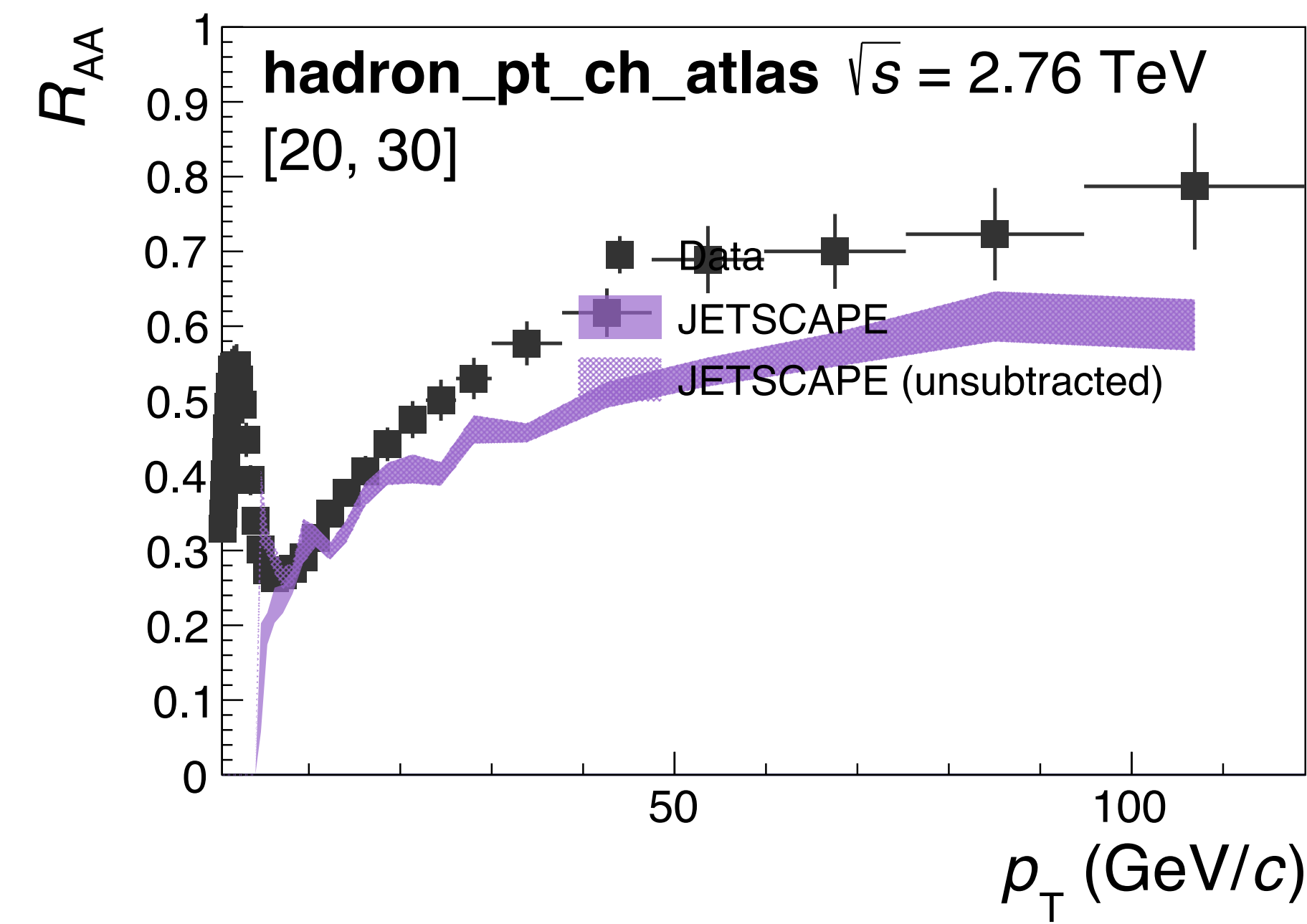


$$P(\theta_h | D_h) \propto P(D_h | \theta_h) \cdot P(\theta_h)$$

► missing uncertainties from θ_s



soft: $w=0.5$ fm + hard: MAP



soft: $w=1.5$ fm + hard: MAP

- ▶ Joint inference (fixed θ_h):

$$P(\theta_s | D_s, D_h) \propto P(D_s, D_h | \theta_s) \cdot P(\theta_s)$$

- ▶ If datasets are independent:

$$P(D_s, D_h | \theta_s) = P(D_h | \theta_s) \cdot P(D_s | \theta_s)$$

- ▶ Sequential inference

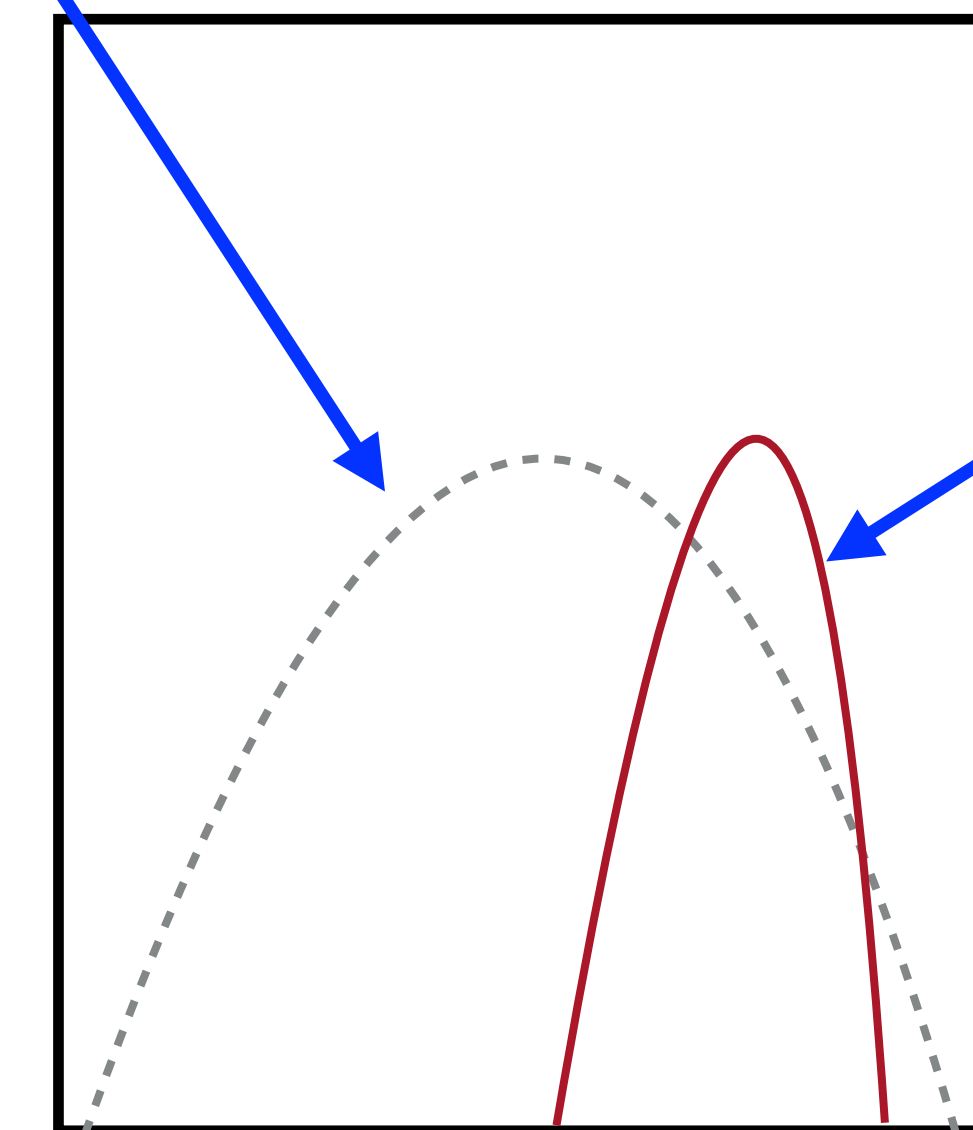
$$P(\theta_s | D_s, D_h) \propto P(D_h | \theta_s) \cdot P(D_s | \theta_s) \cdot P(\theta_s)$$

$$= \underbrace{P(D_h | \theta_s)}_{\text{second inference}} \cdot \underbrace{[P(D_s | \theta_s) \cdot P(\theta_s)]}_{\text{first inference}}$$

- ▶ Update knowledge of θ_s with new data D_h

first inference
from soft sector
observables

second inference
from hard sector
observables



soft sector parameters